



### **NEW EQUIPMENT WARRANTY**

We warrant that this equipment from U.S. Stoneware Corporation is within stated specifications and is free from defects in materials and workmanship.

Our obligation under this warranty is limited to repairing or replacing F.O.B. our factory and defective parts in this product that to our satisfaction existed at time of shipment, provided the purchaser gives us written notice immediately upon discovery thereof, or in any event within one year from time of shipment.

Our warranty does not cover work or replacement of parts made necessary by carelessness, misuse, accident or by incidents which occur outside of use of the instrument such as water damage, lightning, etc. U.S. Stoneware's liability under this warranty shall not exceed the cost of correcting defects whether it is the correction of the defects or the replacement of the product. Claims based on any defect must be made in writing within 30 days of the purchaser's becoming aware of that defect for this warranty to apply. U.S. Stoneware assumes no liability for consequential or special damages in connection with this contract.

U.S. Stoneware shall have no liability for damages of any kind arising from the installation and / or use of this equipment by anyone. The purchaser, by the acceptance of this equipment, will assume all liability for any damages which may result from its use or misuse.

This is our sole warranty with respect to this equipment. We make no other warranty of any kind whatever, express or implies, and all implied warranties of merchantability and fitness for a particular purpose which exceeds the above obligations are hereby disclaimed by U.S. Stoneware Corporation.

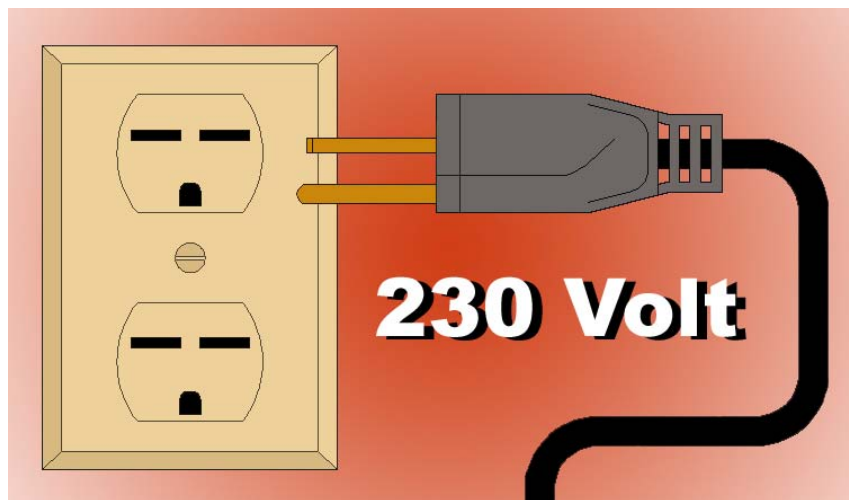


## *~ Voltage Requirement Notice ~*

*This machine is listed for 230 volt single phase input.*

*It will accept +/- 15% of the listed input voltage.*

*It is also capable of accepting 50 or 60 Hz input.*





## INSTRUCTIONS FOR INSTALLATION, OPERATION AND MAINTENANCE OF 801 SERIES JAR MILLS

### INSTALLATION:

- \* After placing machine in the desired location, position it so that the rolls are level.
- \* Line cords are furnished for 115 or 230 volt, single phase AC power supply.  
(Machine controls are compatible for 50 or 60 Hz. operation)
- \* On/Off rocker switch is located on the line cord and a toggle switch is on the controller.  
*Note: Proper rotation should be such that the top of the drive roller turns toward the jar being turned. (CW rotation when viewed from drive end of roller)*

### OPERATION:

- \* Refer to the enclosed chart to adjust the idle roller to the size of jar being used.
- \* To adjust the idle rollers, remove the wing nuts, etc. from the underside of the securing bolts and move the roller to desired location. Replace the bolts, wing nuts, etc.
- \* Roller speed is controlled by the speed pot on the control box.

### LUBRICATION:

- \* The motor and bearings are lubricated for life.
- \* Speed reducer – Oil changes are not required. Oil should only be replaced when maintenance is performed that requires disassembly.  
If the oil is replaced, use Mobil SHC634.
- \* Roller Chain - lubricate bi-weekly with an SAE #30 weight oil.  
*Note: New chains will loosen up slightly as the joints seat themselves causing initial elongation which is many times greater than the elongation during the balance of chain life. A tensioner is located on the upper tier chains to keep the chain taut as it may slacken. To adjust the tension on these chains, loosen the set screw on the tensioner arm, rotate the assembly further into the chain, and re-tighten the set screw. To adjust the tension of the chain from the reducer to the first tier, loosen the four jam nuts on the underside of the machine, evenly tighten the four cap screws located at the corners of the drive mounting plate, then re-tighten the jam nuts on the bottom of the machine.*

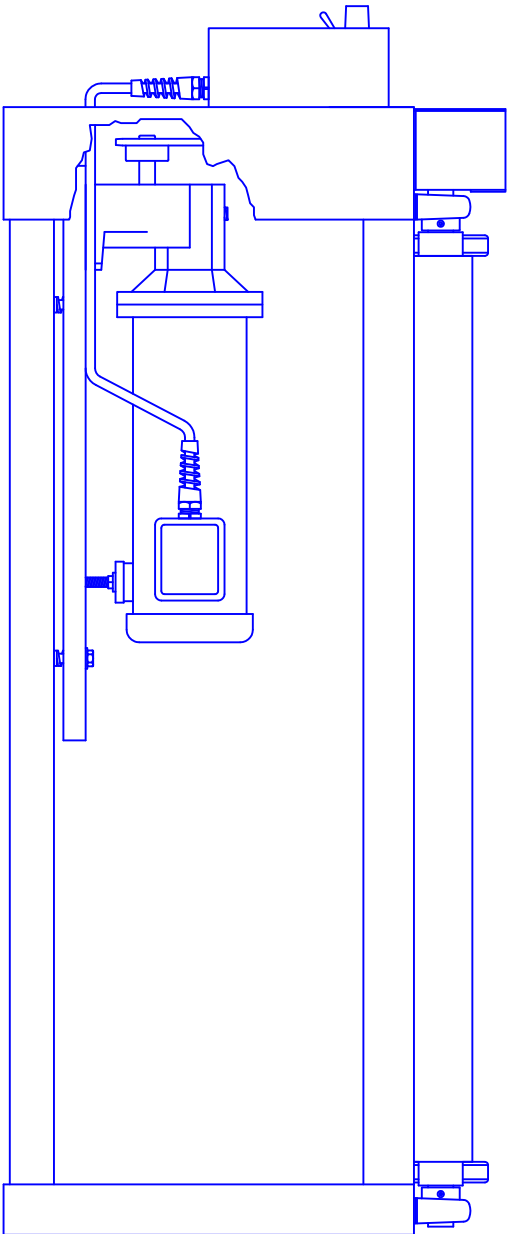
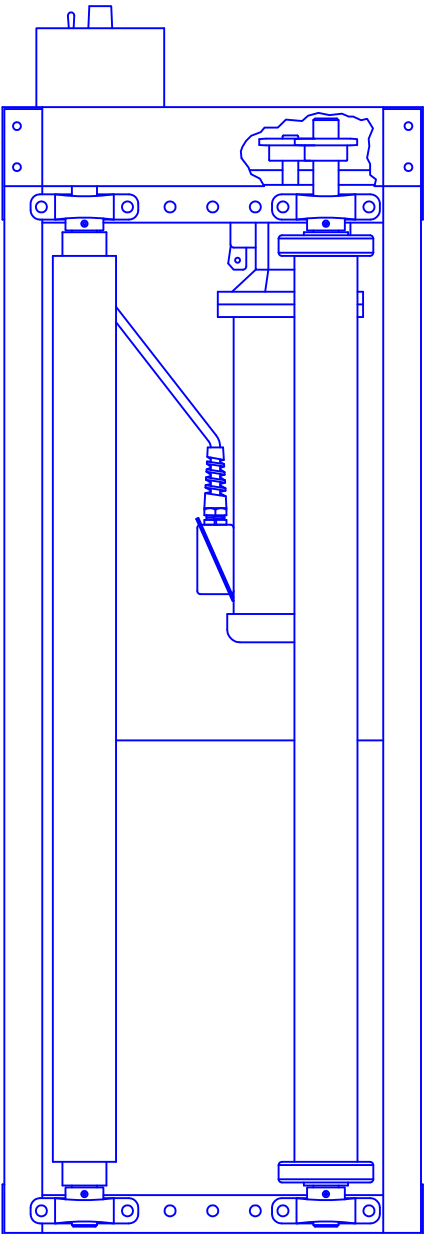
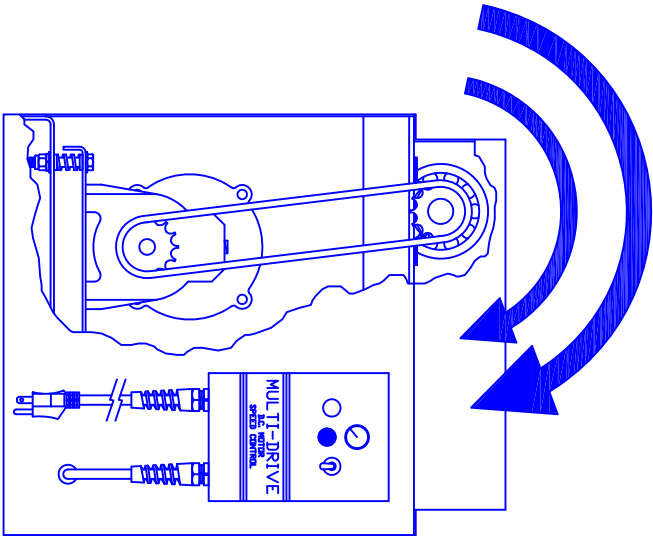
### REPLACEMENT PARTS:

- \* Parts can be identified by referring to the assembly drawing / bill of material.  
Please furnish part number, part name, and serial number of the machine when ordering replacement parts

***Thank You For Purchasing A Quality U.S. Stoneware Product!***

ARROWS INDICATE THE PROPER  
ROTATION FOR THE DRIVE ROLLER  
ON ALL JAR MILL MODELS.

IF THE ROLLER IS TURNING IN THE  
OPPOSITE DIRECTION THE MACHINE  
WILL HAVE THE TENDENCY TO  
"THROW" THE VESSEL BEING TURNED,  
OR EXCESSIVE "WALKING" OF THE  
VESSEL WILL OCCUR.



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SCALE: N/A

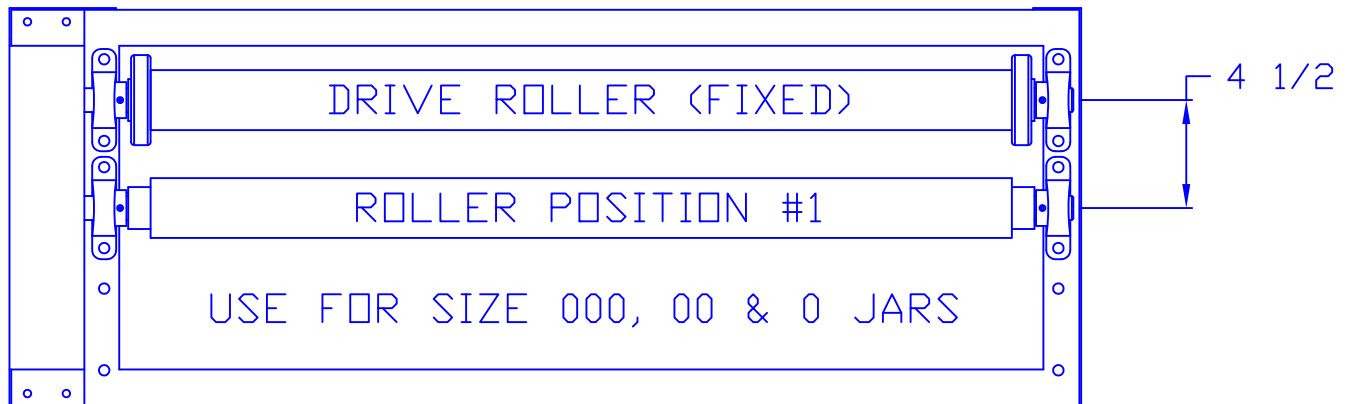
DRAWING OF:  
CORRECT DRIVE ROTATION  
FOR ALL JAR MILLS

DATE	10/30/2008
DESIGNED BY	XXXX
DRIVEROTATION	

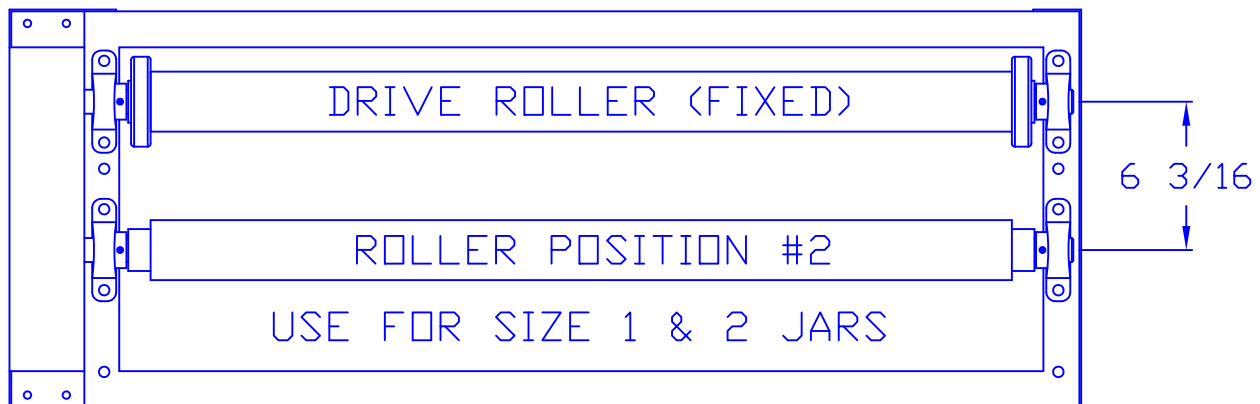
MANUFACTURING STANDARDS	
ALL WELDS TO CONFORM TO AWS D1.1-LATEST REVISION	
UNTOLERANCED FABRICATED DIMENSIONS	
PROPRIETARY NOTICE	
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EXCLUSIVELY OF U.S. STONWARE	
AND ARE NOT TO BE REPRODUCED OR	
UTILIZED IN WHOLE OR PART OR ANY UNAUTHORIZED	
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X = +.020	
XX = +.010	
XXX = +.005	
FRACTIONS = +1/32	
ANGLES = +1/2	

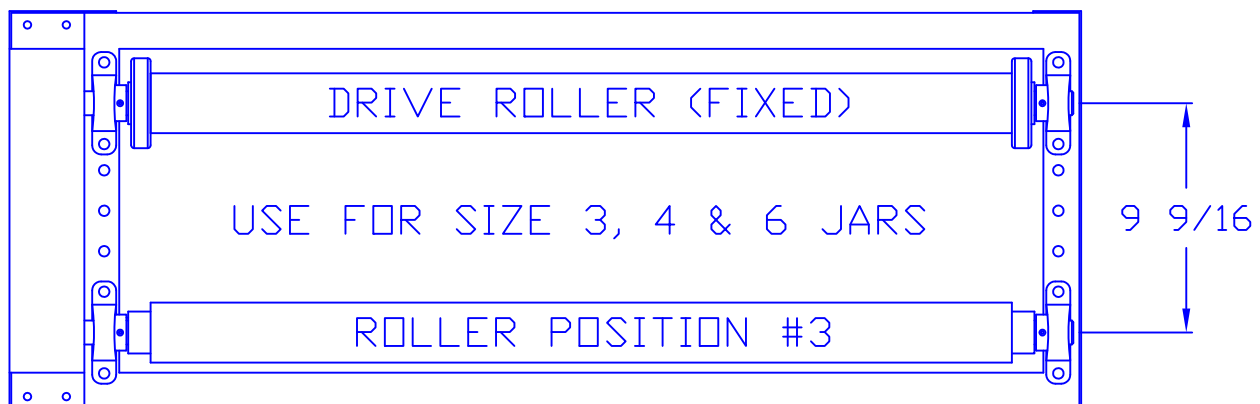
# 800 SERIES ROLLER POSITIONS



( $2 \frac{1}{2}$ " TO 6" DIAMETER)



(6" TO  $9 \frac{1}{2}$ " DIAMETER)



( $9 \frac{1}{2}$ " TO 15" DIAMETER)



**Approximate Roller Speed Settings  
For 800 Series Jar Mills**

<i>Dial Position</i>	<i>R.P.M.</i>
0	50
5	60
10	74
15	85
20	99
25	112
30	125
35	136
40	150
45	163
50	175
55	187
60	200
65	213
70	225
75	237
80	249
85	262
90	274
95	288
100	300



**Recommended Jar / Roller Speeds  
For Optimum Grinding Efficiency**

<b>Jar Model &amp; Size</b>	<b>Recommended Jar Speed</b>	<b>Roll Speed (700 Series)</b>	<b>Roll Speed (800 Series)</b>
774 – 000	106.46	180	144
774 – 00	77.14	222	177
774 – 0	75.28	235	188
774 – 1	60.98	274	220
774 – 2	54.54	300	240
774 – 3	49.79	N/A	259
774 – 4	46.10	N/A	277
774 – 6	46.10	N/A	277
773 – 00	75.28	240	192
773 – 1	60.98	288	230
773 – 3	51.14	N/A	266
611 – 00	72.63	218	174
611 – 0	72.63	218	174
611 – 1	62.39	250	200
611 – 2	55.56	278	222
611 – 3	55.56	278	222
611 – 4	50.56	N/A	243
611 – 6	46.70	N/A	262
612 – 00	72.92	229	183
612 – 0	72.92	229	183
612 – 1	62.59	261	209
612 – 2	55.69	284	227

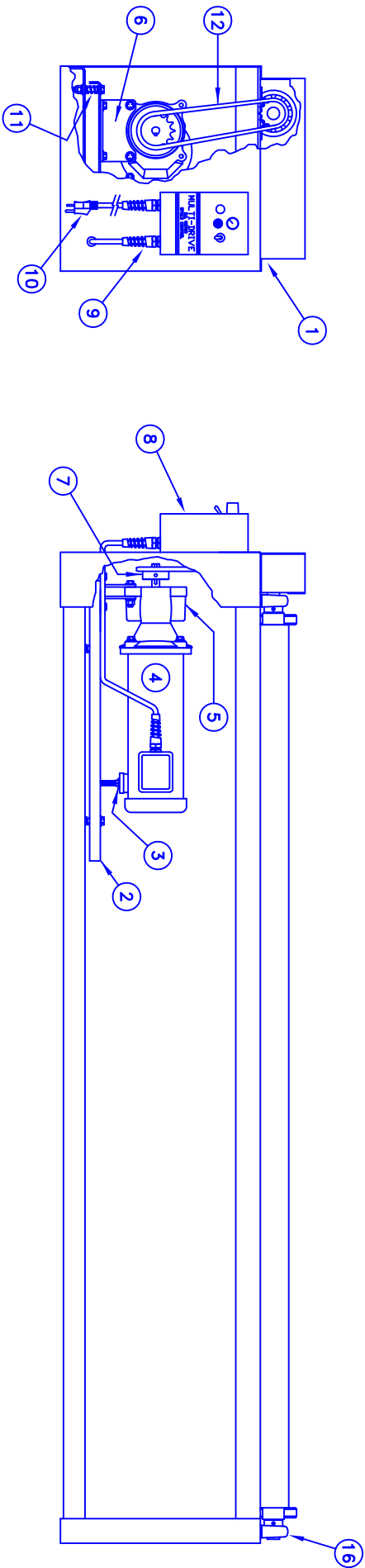
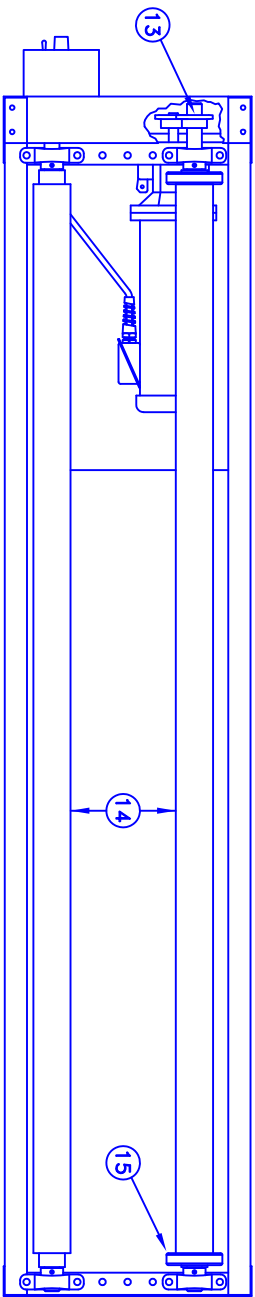
774 – Roalox

773 – High Alumina

611 – Stainless Steel

612 – Rubber Lined Carbon Steel Jar

N/A – Jar Size Not Recommended For This Machine



BILL OF MATERIAL FOR: M93811TDC23

DATE: 04/13/2012

ITEM	QTY.	PART NUMBER	DESCRIPTION
1	1	P90506	MACHINE BASE WITH GUARD
2	1	P90421	MOTOR MOUNT PLATE
3	1	P05401	LEVELER
4	1	EL0036	MOTOR – 3/4 HP – 90V DC.
5	1	P07823DC	REDUCER – 5:1
6	1	P08147	MOUNTING FEET FOR REDUCER
7	1	P08100	SPROCKET – 50B14 X 5/8
8	1	EL0038	CONTROL
9	3	P06441-P	STRAIN RELIEF
10	1	P26314-1	LINE CORD – 230/60/1
11	4	P32436	SPRING
12	38	P06254	#50 ROLLER CHAIN
13	1	P08114	SPROCKET – 50B14 X 1
14	2	P07185	DRIVE / IDLE ROLL – 2 1/2 X 72
15	2	P06706	JAR STOP BEARING
16	4	P06603	PILLOW BLOCK – 1”

VOLTAGE REQUIREMENTS: 230/60-50/1

ROLLER R.P.M.: 50 – 300

ALL WELDS TO CONFORM TO AWS D11.1-LATEST EDITION	
UNTOLERANCED FABRICATED DIMENSIONS	
X =	+0.00
XX =	+0.01
XXX =	+0.05
FRACTIONS =	+1/32
ANGLES	= +1/2

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JOB NO.	
SCALE: NONE	
DRAWING OF:	GENERAL ASSEMBLY AND PART ID
FOR	801 FVM JAR MILL
230 VOLT	
DATE: 04/13/2012	
BY: XXXX	
CHECKED BY: XXXX	
PTID801FVM23	





## Replacing Brushes in DC Motors

*Note: Depending on model, the motor may have to be removed for accessibility.*

- 1.) Locate, and remove the two plastic caps or metal covers near the rear of the motor.
- 2.) Carefully remove the brushes from the motor; they will be under a slight spring tension.
- 3.) Using a can of compressed air or equivalent, blow out the excessive carbon dust from inside the motor and inspect the armature inside the motor for wear or damage.

(Always wear the proper personal protective equipment)

- 4.) Place a new set of brushes in the motor making sure they are set properly.
- 5.) Replace the protective caps or metal covers and secure with the screws.

*Worn out brushes will cause the motor to loose power, run intermittently and cause damage to the armature.*

***Brushes should be checked periodically for wear. (Minimum of twice a year)***



## **Separating C-Face Style Reducers From Motors**

Disconnect all electrical power to the machine.

Disconnect wiring to the motor / reducer combination.

Remove the motor / reducer combination from machine base.

Placing the unit on a secure working area, remove the four (4) bolts securing the two units together. (These are the only fasteners holding these parts together)

Holding onto the motor and the reducer bodies, gently rotate and pull the two pieces to break free from each other.

Once the motor and reducer begin to separate, a continued straight line of pull is important to keep the units from binding against each other.

In the event the two parts are, or become stuck or galled together, use two "standard" screwdrivers (180 degrees from each other) to gently and evenly pry the motor and reducer apart.

The use of a penetrating / lubricating spray may be required to assist with the separation of the parts.

**MULTI-DRIVE™**  
**Solid State**  
**DC Motor**  
**Speed Control**  
With  
**Adj. Acceleration**  
**& Deceleration**

**Installation**  
**and**  
**Operating**  
**Instructions**

See SAFETY WARNING on page 4.

**Model KBMD-240D**



KB Part No.  
9370A

- Dual Voltage Input (120V or 240V)
- Up to 1HP-120V & 2HP-240V with Auxiliary Heatsink\* (P/N 9861)
- Multiple Horsepower capability with Plug-In Horsepower Resistor® (Supplied Separately)
- Forward-Brake-Reverse Switch (P/N 9860) (Optional)
- Rugged NEMA 1 enclosure
- Contains AC Line and Armature Fusing\*\*
- Patented KBMM Speed Control Module
- Current Limit LED Indicator

\* Rating without Heatsink is 3/4HP at 120V and 1-1/2HP at 240V.  
\*\* Armature Fuse supplied separately.



**PENTA KB POWER™**

A COMPLETE LINE OF MOTOR DRIVES

© 1997 KB ELECTRONICS, INC.

## IMPORTANT

**Read these simplified instructions before operating control.**

(Remove (2) 6-32 screws and slide off front cover.)

- Set the Dual Voltage Switch to the correct AC line input voltage, "115" or "230."
- Install the correct Plug-In Horsepower Resistor® according to input voltage and motor horsepower (see chart)—Table 3, page 3.
- Install proper size Armature Fuse—(see Fuse Selection Chart).
- Install Auxiliary Heatsink on controls used with motors rated above 3/4 HP on 120 volts and 1-1/2 HP on 240 volts.
- Recheck connections: AC line to L1 and L2; armature to A+ and A-; and field (Shunt motor only) to F+ and F-. Connect ground via ground screw. (Note if motor runs in improper direction reverse armature leads.)
- Nominal trimpot settings are as follows (expressed in % of full CW rotation):

**Table 1**

MIN (minimum speed):	15%
MAX (maximum speed):	60%
IR (IR compensation):	15%
CL (current limit/torque):	65%
ACCEL (acceleration start):	20%
DECEL (deceleration):	20%

- (For detailed instructions see Selection IV, pages 9 & 10.)

**FOR TECHNICAL ASSISTANCE CALL TOLL FREE (OUTSIDE FLORIDA ONLY) 1-800-221-6570.**

### LIMITED WARRANTY

For a period of 18 months from date of original purchase KB will repair or replace without charge devices which our examination proves to be defective in material or workmanship. This warranty is valid if the unit has not been tampered with by unauthorized persons, misused, abused, or improperly installed and has been used in accordance with the instructions and/or ratings supplied. The foregoing is in lieu of any other warranty or guarantee expressed or implied, and we are not responsible for any expense (including installation and removal), inconvenience, or consequential damage, including injury to any person, caused by items of our manufacture or sale. Some states do not allow certain exclusions or limitations found in this warranty so that they may not apply to you. In any event, KB's total liability, under all circumstances, shall not exceed the full purchase price of this unit. (Rev. 10/84)

The information contained in this brochure is intended to be accurate. However, the manufacturer retains the right to make changes in design which may not be included herein.

## Multi-Drive<sup>®</sup> is versatile.

### • DUAL AC VOLTAGE

1. The basic Model KBMD-240D has dual AC line voltage input capability\*\* which provides 0-full speed capability on DC motors from 1/100th-3/4 HP at 120 VAC and 1/50th-1-1/2 HP at 240 VAC (set the Dual Voltage Switch to the corresponding input voltage "115" or "230").

### • HORSEPOWER EXTENDER

2. Add the KB Auxiliary Heatsink to increase the horsepower



KBMD-240D

KBMD-240D  
With Auxiliary  
Heatsink  
& FWD-BRK-REV Switch



capability to 1/100th-1 HP at 120 VAC and 1/50-2 HP at 240 VAC. KB Part No. SC-9861.

### • ALL MOTOR SIZES

3. Multi-Drive<sup>®</sup> adapts to a complete range of motor horsepower by selecting and installing the proper Plug-In Horsepower Resistor<sup>®</sup> (see chart).

### • REVERSIBLE

4. A FWD-BRK-REV Switch Kit is available as an option.



KB Part No.  
SC-9860

Forward Brake  
Reverse Switch



Plug-In  
Horsepower  
Resistor<sup>®</sup>

NOTE: An optional FORWARD-BRAKE-REVERSE Switch is available.

TABLE 2. ELECTRICAL RATINGS\*

MODEL NUMBER	AC LINE VOLTAGE (VAC)**	MOTOR VOLTAGE (VDC)***	AC LOAD CURRENT (RMS AMPS)	DC LOAD CURRENT (AVG. AMPS)	MAX. HP
KBMD-240D Without Auxiliary Heatsink	120	90-130	12.0	8.0	3/4
	240	180	12.0	8.0	1-1/2
KBMD-240 With Auxiliary Heatsink	120	90-130	16.0	11.0	1
	240	180	16.0	11.0	2

\* The Multi-Drive<sup>®</sup> can be converted to the higher rating by installing KB's Auxiliary Heatsink.

\*\* The Multi-Drive<sup>®</sup> must be set for either 120 V or 240 VAC line voltage input by setting the Dual Voltage Switch to "115" or "230". When the control is set for "115" use only 90-130 VDC rated motors. When the control is set for "230" use only 180 VDC rated motors.

\*\*\* The Multi-Drive<sup>®</sup> also supplies field voltage for shunt motors as follows:

On 120 VAC line, field voltage is 100 VDC using F-, F+ and 50 VDC using L-, F-  
On 240 VAC line, field voltage is 200 VDC using F-, F+ and 100 VDC using L-, F-

TABLE 3. PLUG-IN HORSEPOWER RESISTOR CHART\*\*\*

PLUG-IN HORSEPOWER RESISTOR* CHART		
AC LINE VOLTAGE		PLUG-IN HORSEPOWER RESISTOR*  (Resistance Value-OHMS) ..
120 VAC	240 VAC	
MOTOR HORSEPOWER RANGE		
ARMATURE VOLTAGE 90-130 VDC	ARMATURE VOLTAGE 180 VDC	
1/100-1/50	1/50-1/25	1.0
1/50-1/30	1/25-1/15	.51
1/30-1/20	1/15-1/10	.35
1/20-1/12	1/10-1/6	.25
1/12-1/8	1/6-1/4	.18
1/8-1/5	1/4-1/3	.1
1/4	1/2	.05
1/3	3/4	.035
1/2	1	.025
3/4	1 1/2	.015
1*	2*	.01

Motor horsepower and armature voltage must be specified when ordering so that proper Horsepower Resistor<sup>®</sup> will be supplied.

\* Use with Auxiliary Heatsink

\*\* For overlapping motor horsepower range use lower value Plug-In Horsepower Resistor<sup>®</sup>.

\*\*\* Customer choice use PWR and avoid recalibration or select one resistor and recalibrate for different motors.

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### SAFETY WARNING—PLEASE READ CAREFULLY

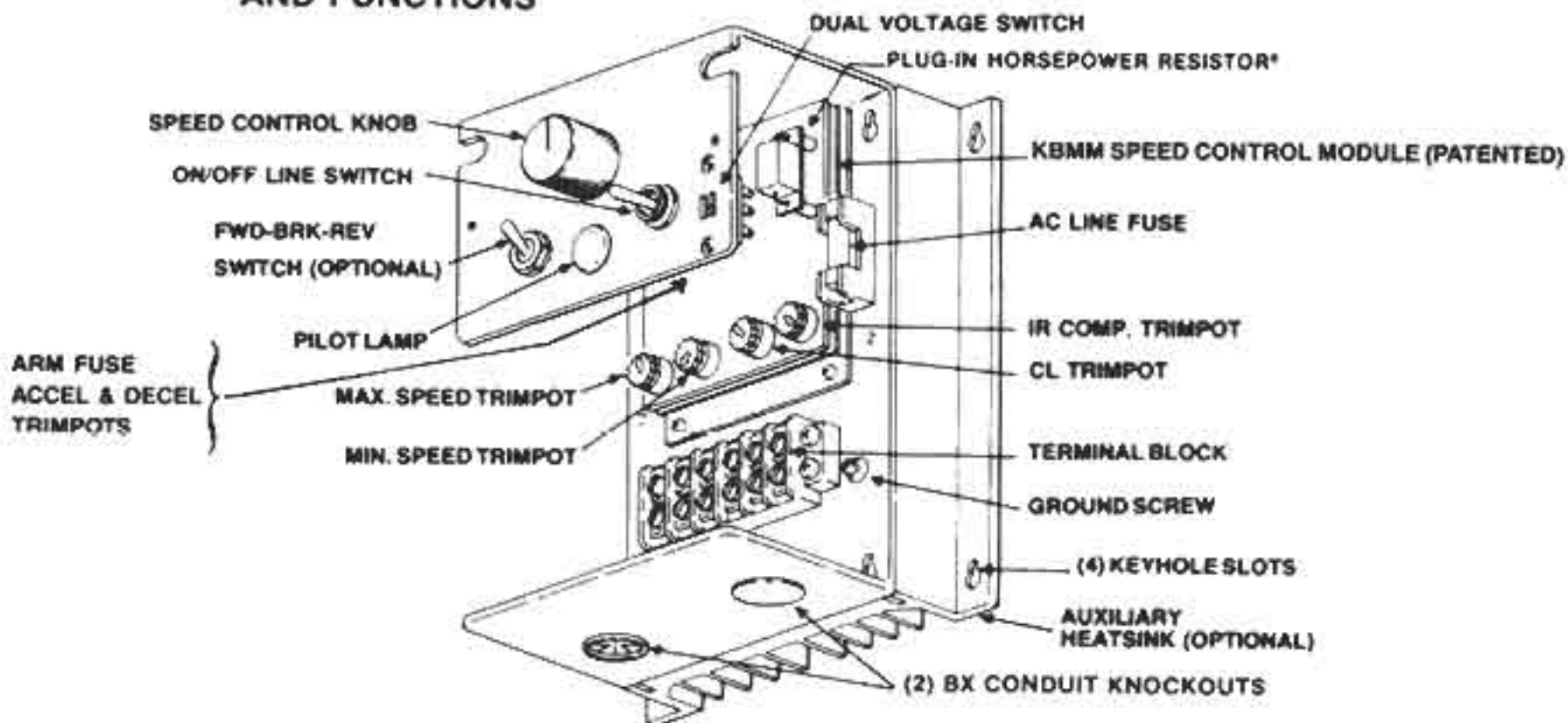
This product should be installed and serviced by a qualified technician, electrician or electrical maintenance personnel familiar with its operation and the hazards involved. Proper installation which includes wiring, mounting in proper enclosure, fusing or other overcurrent protection and grounding, can reduce the chance of electric shocks, fires or explosion in this product or products used with this product, such as electric motors, switches, coils, solenoids and/or relays. Eye protection must be worn and insulated adjustment tools must be used when working with control under power. This product is constructed of materials (plastics, metals, carbon, silicon, etc.) which may be a potential hazard. Individual material safety data sheets (MSDS) are available upon request. Proper shielding, grounding and filtering of this product can reduce the emission of radio frequency interference (RFI) which may adversely affect sensitive electronic equipment. If information is required on this product, contact our factory. It is the responsibility of the equipment manufacturer and individual installer to supply this safety warning to the ultimate user of this product. (SW effective 7/89)



**TABLE 4. GENERAL PERFORMANCE SPECIFICATIONS**

Speed range (ratio)	50:1
Load regulation (% base speed) (0-full load; 50:1 speed range)	1*
Line voltage regulation (% base speed) (at full load; 100-130 VAC)	1/2*
Control linearity (% speed vs. dial rotation)	2
CL/torque range (% full load)	0-200
ACCEL/DECEL time period (0-full speed) (secs.)	.2-10
Min. speed trimpot range (% full speed)	0-30*
Max. speed trimpot range (% full speed)	50-110*
IR compensation trimpot range (at specified full load) (volts)	0-24
Maximum allowable ambient temperature at full rating (°C/°F)	50/122

\*Performance is for SCR rated PM motors only. Lower performance can be expected with other motor types. Factory setting is for 3% load regulation. To obtain superior regulation, see Sec. IV E. (page 10). Other factory trimpot settings are as follows: CL-150% FL, ACCEL-2 secs., DECEL-2 secs., MIN-(0)-speed, MAX-full speed & IR-6 volts.

**FIG. 2 LOCATION OF FEATURES  
AND FUNCTIONS**

# INTRODUCTION

The New Multi-Drive<sup>®</sup> Full Wave Solid State DC Motor Speed Control with the patented KBMM Speed Control Module represents the latest state-of-the-art design achievable through modern technology.

**Features Include:** Short circuit protection, CL LED Indicator, Auto Inhibit.

- **Integrated Circuitry**

Used to control and amplify command and reference levels with both closed and open loop feedback to provide superior motor regulation. (Speed changes due to load, line voltage, or temperature variations are held to minimum levels).

- **High Quality Components**

Selected and tested for proven dependability.

- **Transient Protection**

Used to prevent failure of the power bridge circuit caused by voltage spikes on the AC line.

- **High Reliability**

When used in accordance with the instructions included in this manual, the Multi-Drive<sup>®</sup> will provide years of trouble-free operation.

## SECTION I. APPLICATION INFORMATION

- A. Motor Type.** Multi-Drive<sup>®</sup> is designed for Permanent Magnet (PM) and Shunt Wound D.C. motors. Controls operated on 120 volt AC inputs are designed for 90 volt SCR rated motors. Controls operated on 240 volt AC inputs are designed for 180 volt SCR rated motors. Use of higher voltage motors will result in degradation of full speed performance. Also, if motor is not an SCR rated type, the actual AC line amperage at full load should not exceed the motor's DC nameplate rating.
- B. Torque Requirements.** When replacing an AC induction motor with a DC motor and speed control, consideration must be given to the maximum torque requirements. The full load torque rating of the DC motor must be equal to, or greater than, that of the AC motor.
- C. Acceleration Start.** The Multi-Drive<sup>®</sup> contains an adjustable acceleration start feature which allows the motor to smoothly accelerate from 0–full speed over a time period of .2–10 seconds. The "ACCEL" is factory set at 2 seconds.
- D. Limitations in Use.** Multi-Drive<sup>®</sup> controls are designed for use on machine applications.

**CAUTION:** Consult factory before using on constant horsepower applications such as saws or drill presses. Do not use in explosive atmosphere.

**CAUTION:** Be sure the Multi-Drive<sup>®</sup> is used within its max. ratings. Follow all installation instructions carefully. (Refer to Section II.)



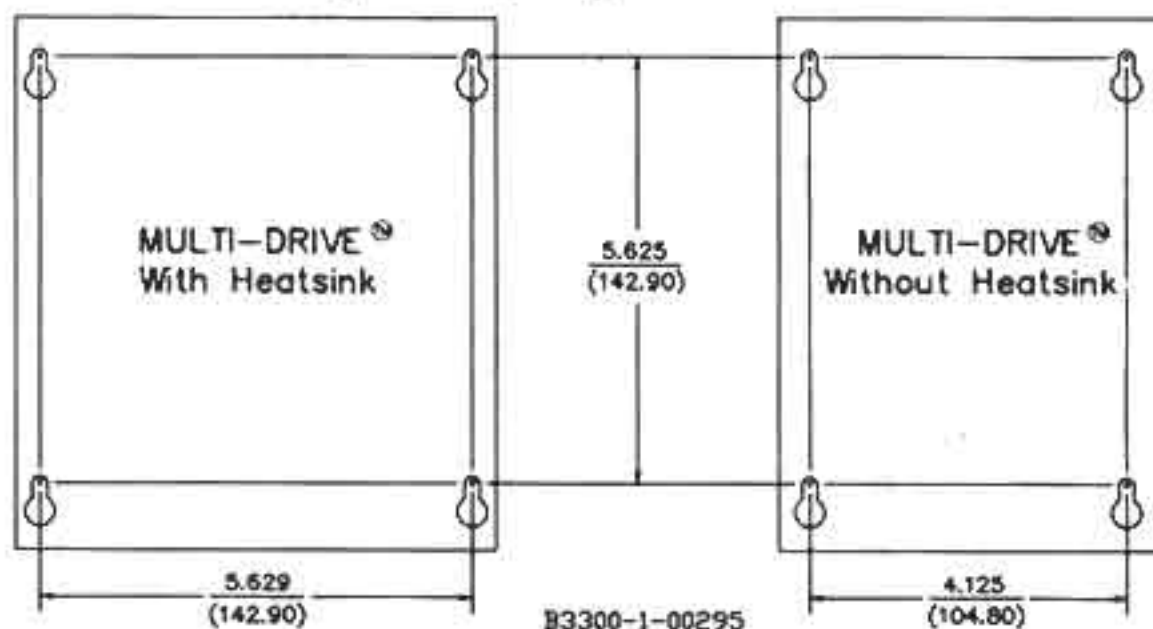
## SECTION II. INSTALLATION INSTRUCTIONS

**A. Location and Mounting.** The Multi-Drive<sup>®</sup> control should be mounted on a flat surface and located in an area where it will not be exposed to contaminants such as water, metal chips, solvents, or excessive vibration.

When mounting in an airtight enclosure, the air space should be large enough to provide adequate heat dissipation. The maximum allowable ambient temperature at full rating is 50°C (122°F). Consult your factory representative if more information is required.

**NOTE:** Adequate clearance must be allowed to permit motor and power cables to enter through BX knockouts on bottom of control.

**FIG. 3 MOUNTING DIMENSIONS (INCHES, MM)**



**B. Initial Setup. WARNING:** To prevent electrical shock turn power off before wiring.

- (1) Slide open front cover by removing two 6-32 screws.
- (2) Install Plug-In Horsepower Resistor<sup>®</sup> corresponding to motor voltage and horsepower. (See chart Table 3, page 3)
- (3) Set the Dual Voltage Switch to proper position "115" or "230" which corresponds to the nominal AC input line voltage 120 or 240 VAC.
- (4) Install proper Armature fuse according to Fuse Selection Chart. (Table 6, page 8)
- (5) Trimpots have been factory adjusted. If readjustment is required see section IV pages 9 & 10.
- (6) Install Auxiliary Heatsink if motor is larger than 3/4 HP on 120 VAC and 1-1/2 HP on 240 VAC. (Use (6) No. 10-32 screws)

**C. Wiring.** (See Fig. 4 for terminal arrangement and wiring information.)

- (1) Connect the Multi-Drive<sup>®</sup> to a standard 120 V or 240 V 50/60 Hz power source. [Be sure the DVS is set to the proper voltage "115" or "230" and motor voltage corresponds to the line voltage. (e.g. 90-130 VDC motor on 115-120 VAC and 180 VDC motor 230-240 VAC)]
- (2) Follow the recommended supply wire sizes as per Table 5. (For Stepdown operation see note on page 8.)
- (3) Follow the NEC and other appropriate electrical codes. **CAUTION:** Separate branch protection must be provided on 240 V circuits.
- (4) Replace front cover and the two 6-32 screws.

TABLE 5. MINIMUM SUPPLY WIRE SIZE REQUIREMENTS.

MAX. MOTOR AMPS (DC AMPS)	MAX. MOTOR HP 90 V	MAX. MOTOR HP 180 V	MINIMUM WIRE SIZE (AWG) Cu Only	
			MAX. 50 FOOT RUN	MAX. 100 FOOT RUN
8.0	3/4	1-1/2	16	14
11.0	1	2	14	12*

\*Maximum recommended wire size

**Application Note:** Stepdown operation: The control can be set up for stepdown operation (e.g.: 90 VDC motors used with 240 VAC line input). If stepdown operation is required, the following procedure is used.

1. Place dual voltage switch in "115" position.
2. Cut out and remove the resistor R308 (large blue body) from the back of the dual voltage switch. For shunt wound motors only—connect motor field wires to F + and L<sub>1</sub> terminals.

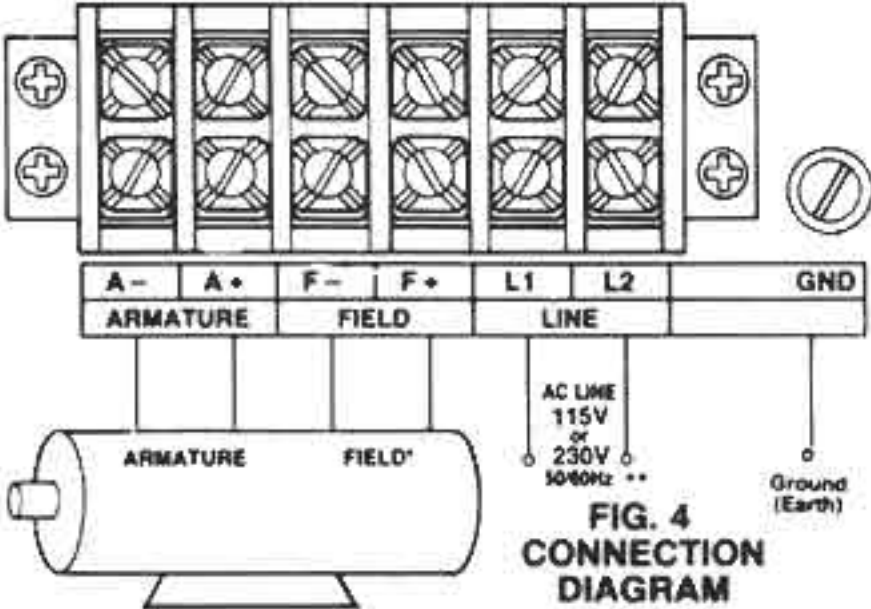


FIG. 4  
CONNECTION  
DIAGRAM

- \* Use F- & F+ for shunt motors only. On motors with half voltage fields (e.g. 50 V field with 100 V rated armature) use L<sub>1</sub> & F+ terminals.
- \*\* Be sure to set the Dual Voltage Switch to the proper position "115" or "230".

TABLE 6. FUSE SELECTION CHART

90 VDC MOTOR	180 VDC MOTOR	APPROX. DC MOTOR CURRENT (AMPS)	FUSE RATING (AC AMPS) ARM	RECOM. RATING (AC AMPS) LINE
HORSEPOWER				
1/30	1/15	.33	1/2	12
1/20	1/10	.5	3/4	12
1/15	1/8	.65	1	12
1/12	1/6	.85	1-1/4	12
1/8	1/4	1.3	2	12
1/6	1/3	1.7	2-1/2	12
1/4	1/2	2.5	4	12
1/3	3/4	3.3	5	12
1/2	1	5.0	8	12
3/4	1-1/2	7.5	12	12
1	2	10.0	15	25

**CAUTION:** If control is wired to a transformer, it is advisable to switch the secondary to disconnect power. If the primary is switched, additional snubber capacitors may have to be added across the transformer output to prevent damage to the power bridge.

**WARNING:** Do not wire switch or relay in series with armature or catastrophic failure will result.

D. Fusing.

- (1) The Multi-Drive<sup>®</sup> contains a built-in replaceable AC line fuse rated 20A-240 VAC. (Use Buss type MDA or equiv.) The AC line fuse protects the control against catastrophic failure. If the fuse blows, the control is miswired, the motor is shorted or grounded, or the Speed Control Module is defective. (Note: jumping of fuse will void warranty)
- (2) Armature Fuse—Provides motor overload protection. Armature fuses are available from your distributor. Fuse at approximately 1.7 times the D.C. amperage rating of the motor. (See Fuse Selection Chart)

### SECTION III. OPERATION

1. Set ON/OFF power switch to "OFF".
2. Set speed control knob to "0".
3. Set FWD-BRK-REV switch (if installed) to "FWD".
4. Turn power switch to "ON" gradually increase speed control knob setting. Motor should come up to speed smoothly and remain stable. (NOTE: If control fails to operate, see Troubleshooting Guide, Section V, p. 11, 12)

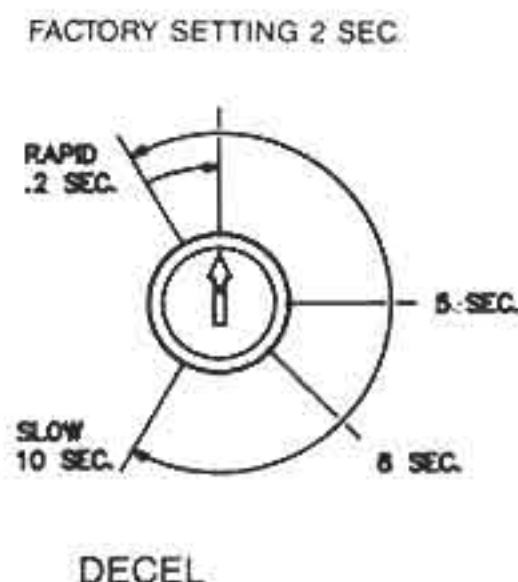
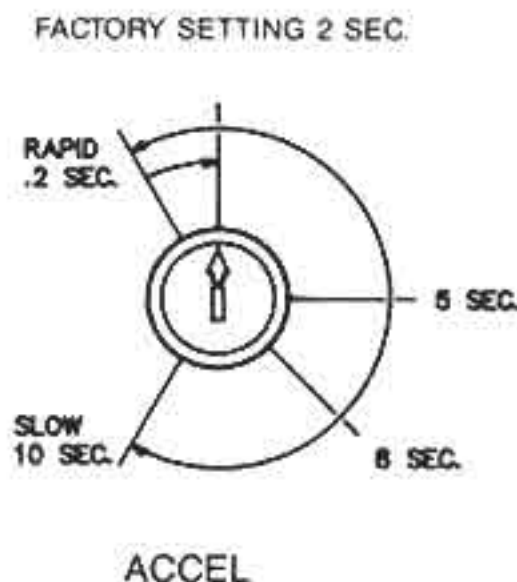
### SECTION IV. ADJUSTMENTS AND CONTROL FUNCTIONS

The Multi-Drive<sup>®</sup> has been factory adjusted to provide 0 to full speed range using the speed control knob. Minimum and maximum speed trimpots are provided to change the speed from other than 0 to full speed. An acceleration start trimpot is factory set to provide motor acceleration from 0 to full speed over a time period of 2 seconds (approx.) each time the AC power is applied. The current limiting (CL, or torque output) adjustment is factory set to approximately one and a half times the motor rating. The IR Compensation (IR) is factory adjusted to provide excellent motor regulation under normal operation.

**NOTE:** In order for the IR comp and CL trimpot settings to be correct, the proper Plug-In Horsepower Resistor<sup>®</sup> must be installed for the particular motor and input voltage being used. Do not attempt to change the settings of the trimpots unless absolutely necessary since they are factory adjusted to near optimum settings.

The following procedure, presented in order of adjustment sequence, should be used when readjusting all trimpot functions:

FIG. 5



- Acceleration Start and Deceleration.** ACCEL and DECEL trimpots are located on the left side of the speed control module. If the ACCEL and/or DECEL are to be readjusted to different times, adjust trimpots according to Figure 5.
- Maximum Speed Adjustment.** Turn Speed Control Knob to full speed (maximum CW position). Adjust max. speed trimpot to new desired setting.

**NOTE:** Do not attempt to adjust the max. speed above the rated motor RPM since unstable motor operation may occur. For moderate changes in the max. speed, there will be a slight effect on the min. speed setting when the min. speed is set at zero. There may be significant variation in the min. speed setting if the min. speed is at a higher than zero setting.

- C. Minimum Speed Adjustment.** If a higher than zero minimum speed is desired, readjust the minimum speed by turning the speed control knob to zero setting (full CCW position). Then adjust the Min. Speed Trimpot to the desired setting.

**NOTE:** The min. speed adjustment will affect the max. speed setting. Therefore, it is necessary to re-adjust the max. speed after the min. speed, and it may be necessary to repeat the sequence until both the min. and max. speeds are set to the desired levels.

- D. Current Limit (CL/Torque Adjustment).** CL circuitry is provided to protect the motor and control against overloads. The CL also limits the inrush current to a safe level during startup. The CL is factory set to approximately 1.5 times the full load rating of the motor. (CL trimpot is nominally set to approx. 75% of full CW rotation.) CL LED will light when control is in current limit.

**NOTE:** The correct value Plug-In Horsepower Resistor\* must be installed in order for the CL and IR comp. to operate properly.

**To set the CL to factory specifications adjust as follows:**

1. Set speed control knob at approximately 30–50% CW rotation. Set CL trimpot to full CCW position.
2. Connect a DC ammeter in series with the armature lead.
3. Lock shaft of motor (be sure CL pot is in full CCW position). Apply power and rotate CL pot CW slowly until DC ammeter reads 1.5 times motor rating (do not exceed 2 times motor rating).

- E. IR Compensation Adjustment.** IR compensation is provided to substantially improve load regulation. If the load presented to the motor does not vary substantially, the IR adjustment may be set at a minimum level (approximately 1/4 of full setting). The control is factory adjusted to approximately 3% regulation if superior performance is desired (less than 1% speed change of base speed from 0 to full load), then the IR comp should be adjusted as follows:

**NOTE:** Excessive IR comp. will cause control to become unstable, which causes motor cogging.

1. Set IR comp. trimpot at approximately 25% of CW rotation. Run motor unloaded at approximately 1/3 speed and record RPM.
2. Run motor with maximum load and adjust IR comp. trimpot so that the motor speed under load equals the unloaded speed per step 1.
3. Remove load and recheck unloaded RPM. If unloaded RPM has shifted, repeat procedure for more exact regulation.

The MULTI-DRIVE™ is now compensated to provide minimal speed change under large variations of applied load.



# SECTION V. TROUBLESHOOTING GUIDE

The following Troubleshooting Guide is intended for use by a qualified technician. The Guide is designed to isolate common malfunctions of the MULTI-DRIVE<sup>®</sup> and/or motor. It should be used with the parts lists and schematics contained in this manual.

SYMPTOM	POSSIBLE CAUSE	CORRECTIVE ACTION
1. Motor does not run; power ON indicator not lit.	1. Power switch in OFF position, or AC voltage not brought to L <sub>1</sub> , L <sub>2</sub> terminals.	1. Move power switch to ON position. Correct wiring to control.
	2. Blown line fuse.	2. Replace line fuse with 20A rated 3AB-type fuse. If fuse blew due to miswiring, speed control module may be defective.
	3. Defective power switch.	3. Replace power switch.
2. Motor does not run; power ON indicator lit.	1. Speed control knob set to 0.	1. Turn knob CW to start motor.
	2. Defective motor.	2. Check for defective motor, worn brushes, etc. Replace motor.
	3. Plug-in Horsepower Resistor <sup>®</sup> not installed.	3. Install proper Plug-in Horsepower Resistor <sup>®</sup>
	4. Blown armature fuse.	4. Replace fuse with proper value.
3. Motor hums, or runs at very low speed (with control knob set at high number) or motor slows down substantially when load is applied.	1. Low voltage.	1. Check line voltage at control and rewire as required.
	2. Overload condition; control in current limit mode (CL trimpot not set correctly). (CL LED lit)	2. Reduce loading; CL trimpot setting may have to be increased. See Section IV.
	3. Plug-in Horsepower Resistor <sup>®</sup> not correct size.	3. Install proper size Plug-In Horsepower Resistor <sup>®</sup>
	4. Incorrect wiring. Armature and shunt connections interchanged (shunt motor only).	4. Correct wiring (armature has lower resistance than field).

## SECTION V. TROUBLESHOOTING GUIDE

### SYMPTOM

### POSSIBLE CAUSE

### CORRECTIVE ACTION

4. Erratic motor performance.

1. Defective motor, worn brushes, etc.

1. Repair motor.

2. Overload condition.

2. Remove overload.

3. Plug-in Horsepower Resistor\*  
wrong size.

3. Replace Plug-in Horsepower  
Resistor\* with proper size.

4. IR comp and/or CL trimpots not  
set properly.

4. Readjust trimpots as per Section IV.

5. Defective speed control module.

5. Replace module.

6. Dual Voltage Switch set in wrong  
position.

6. Recheck line voltage and set Dual  
Voltage Switch to proper position  
"115" or "230".

5. Motor continues to run when speed  
control knob is set to 0.

1. Min. speed trimpot not set to full  
CCW position.

1. Readjust min. trimpot.

2. IR comp trimpot set too high.

2. Lower IR comp trimpot setting.

6. Motor runs in wrong direction.

1. Armature leads reversed.

1. Reconnect armature leads.

The following portion of the Troubleshooting Guide refers only to controllers that have the FWD-BRK-REV switch option.

### SYMPTOM

### POSSIBLE CAUSE

### CORRECTIVE ACTION

1. Motor will not run in either forward  
or reverse direction.

1. Faulty wiring or loose connections  
to reversing switch.

1. Correct wiring (see internal wiring  
diagram).

2. Defective FWD-BRK-REV switch.

2. Replace switch assembly.

2. No braking action in brake mode.

1. Faulty wiring or loose connection.

1. Correct wiring.

2. Faulty FWD-BRK-REV switch.

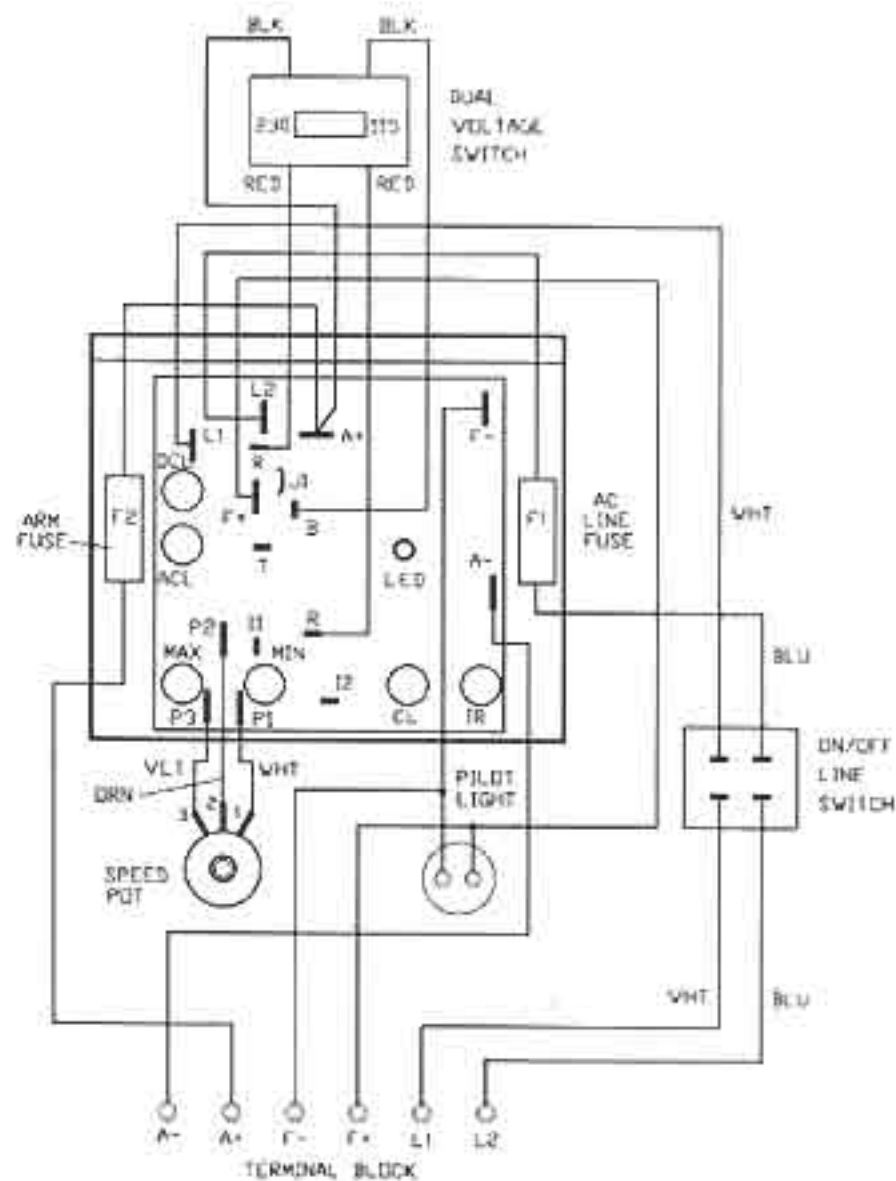
2. Replace switch assembly.

3. Defective Brake Resistor.

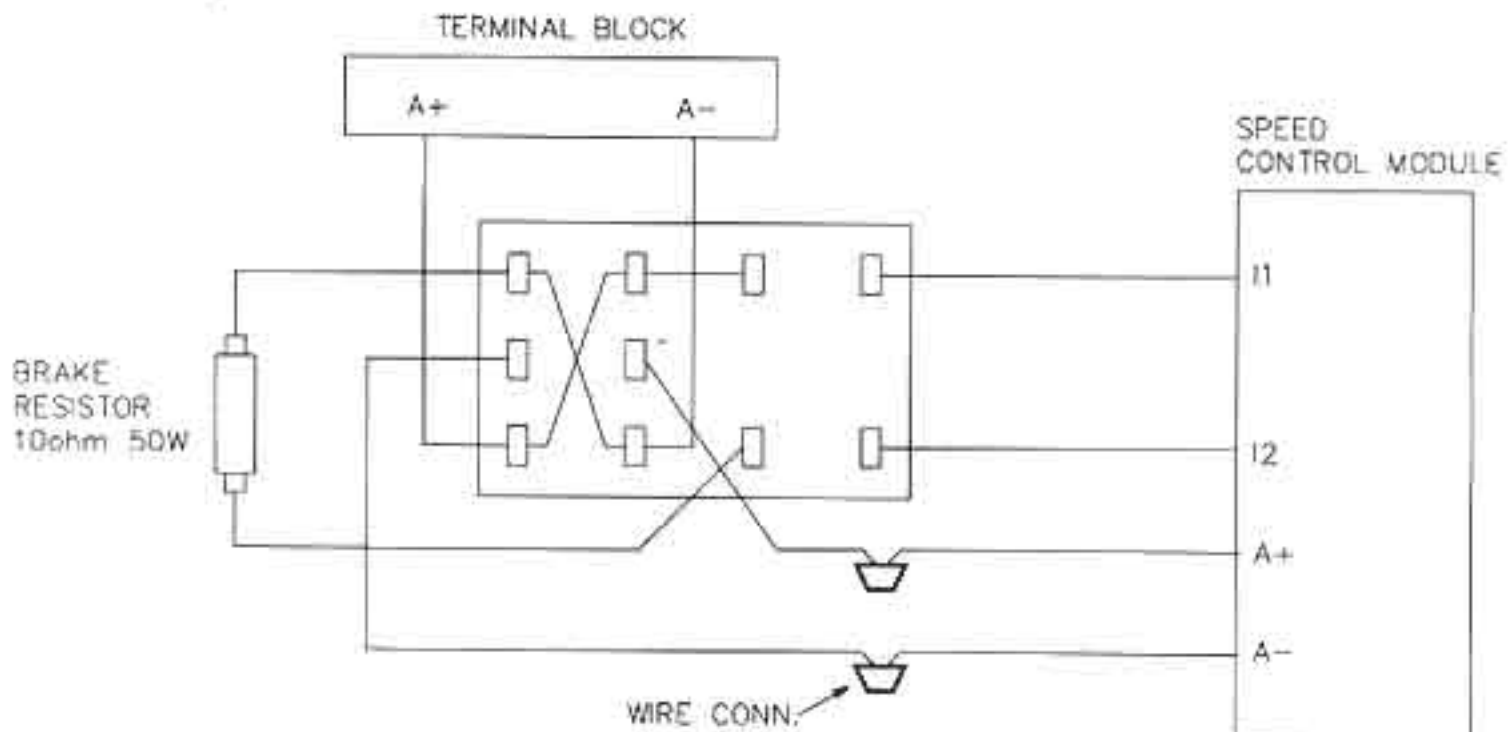
3. Replace resistor.

**SECTION VI. (A) INTERNAL  
WIRING DIAGRAMS**

**1. BASIC MULTI-DRIVE®**



**2. FORWARD-BRAKE-REVERSE  
SWITCH (OPTIONAL)**



# BALDOR

## BALDOR ELECTRIC COMPANY

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### RATIO MULTIPLIER INSTALLATION, LUBRICATION AND OPERATION INSTRUCTION

*These instructions must be read thoroughly before installing or operating speed reducers. File instructions for future reference.*

#### CAUTION

- For safe operation of any gear drive, all rotating shafts and auxiliary components must be shielded to conform with applicable safety standards. You must consider overall operational system safety at all times.
- When using a speed reducer to raise or lower a load, such as in hoisting applications, provision must be made for external braking. Under no conditions should a speed reducer be considered self-locking.
- Mounting of speed reducers in overhead positions may be hazardous. Use of external guides or supports is strongly recommended for overhead mounting.

#### GENERAL INSTRUCTIONS

Align all shafts accurately. Improper alignment can result in failure. Use of flexible coupling is recommended to compensate for slight misalignment.

Auxiliary drive components (such as sprockets, gears and pulleys) should be mounted on the shafts as close as possible to the housing to minimize effects of overhung loads. Avoid force fits that might damage bearings or gears.

Gear drives are nameplated for 1750 RPM Input Speed and Class I Service. For lower Input Speeds and other Service Classes, consult the factory.

#### INSTALLATION

Baldor Ratio Multipliers are ready for installation as removed from the carton. Each Ratio Multiplier has been filled with Klubersynth GH6-460 synthetic lubricant at the factory. The oil quality is sufficient for any mounting position. The motor shaft coupling has been prelubricated with Kluber Q NB 50 antiseize.

#### MOUNTING POSITION

For maximum seal life, the Ratio Multiplier should be mounted with the input shaft as high as possible. ***Mounting the Ratio Multiplier with the input seal vertically down is not recommended.*** If a vertically down input shaft position is required, consult the factory.

#### LUBRICATION

Oil changes are not required. Oil should only be replaced when maintenance is performed that requires disassembly. If the oil is replaced, use Klubersynth GH6-460. This Lubrication is suitable for a wide temperature range (-31°F to 320°F). However refer to "Operating Environment" section for ambient operating temperature for Baldor ratio multipliers.

(Oil capacity in fluid ounces ***RM1 6.2 oz., RM2 11 oz.***)

Satisfactory performance may be obtained with non-synthetic oils and will require more frequent changes.

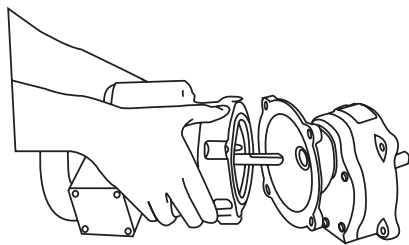
#### OPERATING ENVIRONMENT

Baldor Ratio Multipliers are designed to operate in ambient temperatures of -10°F to 100°F. The oil sump temperatures of the Ratio Multiplier must not exceed 200°F. Consult the factory for applications requiring ambient operating temperature outside this range.

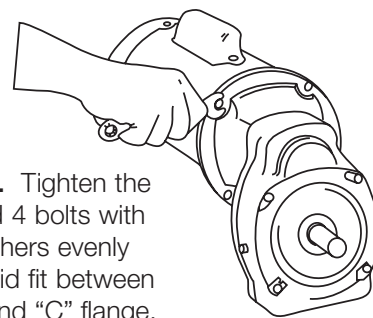


## **“C” FLANGE – HOLLOW BORE WORM STYLE:**

**STEP #1.** Remove bore plug. Position key in Ratio Multiplier Input Bore. Line up the key with the keyslot and slip the motor shaft into the Ratio Multiplier Input Bore.



**STEP 2.** Tighten the supplied 4 bolts with lockwashers evenly for a solid fit between motor and “C” flange.



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## **EXTENDED “C” FLANGE WITH FLEXIBLE COUPLING STYLE:**

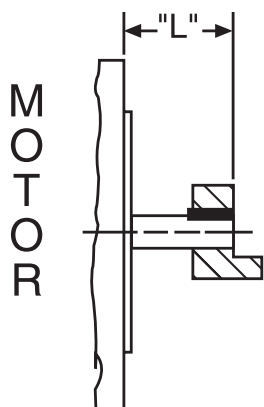
**STEP #1:** Mount one coupling half on motor shaft so that the coupling half and end of key are flush with end of motor shaft. (See Drawing A)

**STEP #2:** Tighten coupling setscrews. Thread locking compound is recommended on all coupling setscrews. Measure distance from inner face of coupling to motor mounting surface. (See Drawing A)

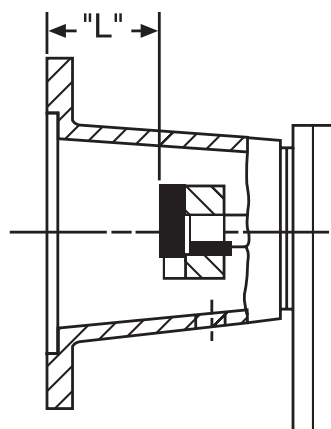
**STEP #3:** Mount other coupling half on the reducer input shaft so the coupling end measures the same distance to the mounting surface of the “C” flange. (See Drawing B) Tighten setscrews. Key should be flush with shaft end. Use pipe plug opening in side of “C” flange to loosen, tighten or make any adjustments in coupling position.

**STEP #4:** Align coupling halves and install motor.

**STEP #5:** Rotate motor to required position and tighten the supplied four bolts and lockwashers evenly for a solid fit between motor and “C” flange. Re-install and tighten the pipe plug in the flange access hole.



**Drawing A**



**Drawing B**